**Virtual Pi2Go Programming: WS8 Sample Answers and Troubleshooting**

**Sample Answer 1:** If there is nothing in front of the robot it does nothing. Otherwise it reverse and keeps printing out “reversing” until it is far enough away from the obstacle to stop.

**Sample Answer 2:** You would need to test it when there is an obstacle in front of it and when there isn’t an obstacle in front of it.



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